

## Acoustics-08 Paris

“Low operating temperature integral systems”

A novel hybrid configuration TA engine

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Aster Thermoakoestische Systemen

General system aspects

Reduction of average regenerator impedance

Novel hybrid configuration

Experimental verification

Conclusions

## General system aspects

- Fixed power driven TA engines

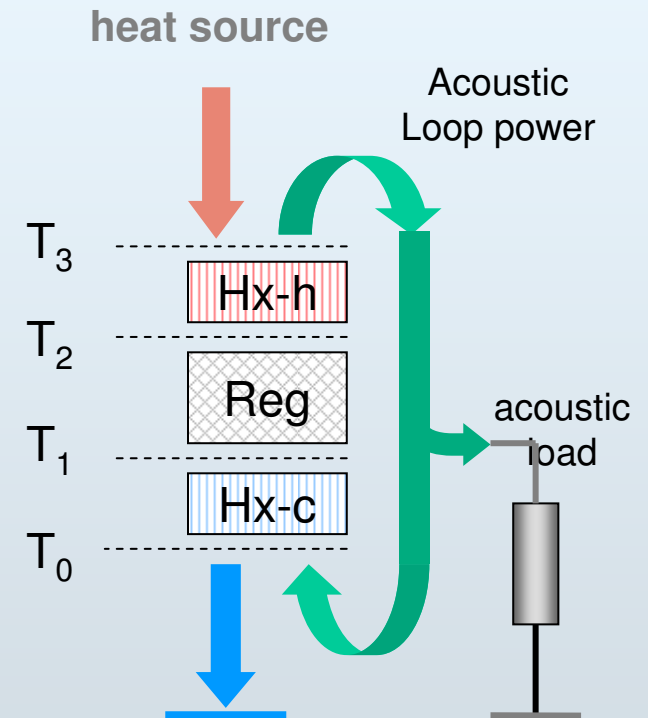
- $T_3 \gg T_2$
- gain “proportional” with load
- Acoustic power  $\approx$  constant
- No or little “hot hex” losses

- Useful in TA experiments
- **Little practical use**

- Fixed temperature driven TA engines

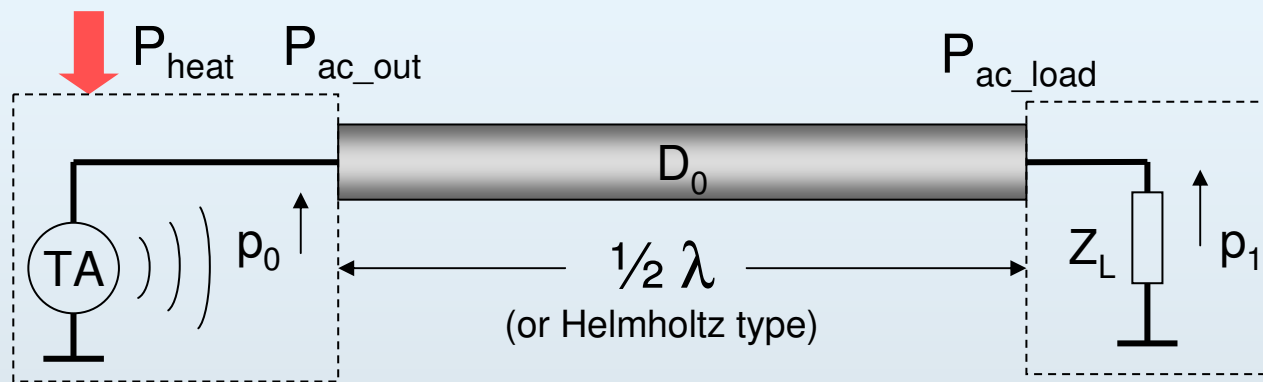
- $(T_3 - T_2) \Rightarrow$  to be minimized
- fixed gain (per stage)
- acoustic power inversely proportional to load
- hex design crucial

**Pertain to nearly all practical applications**



## General system aspects

- Loop, transferred and available power



### Minimize ratio acoustic loss / transferred power

Two way strategy

#### 1. Minimize acoustic losses

- Avoid high local amplitude (no standing waves)
- Shape and wall finish (in turbulent regime only)
- **Lower limit** by thermal and viscous boundary layer losses !

#### 2. Maximize transferred or loop power

- Decrease average regenerator and load impedance

$$P_{ac\_loop} = \frac{A_{reg} \cdot p_0^2}{2 \cdot \text{Re}(Z_{reg})}$$

$$P_{ac\_out} = P_{ac\_loop} \cdot \left( \frac{T_H}{T_C} - 1 \right)$$

$$P_{Loss\_lam} \approx \alpha \cdot p_0^2 \cdot A_{wall}$$

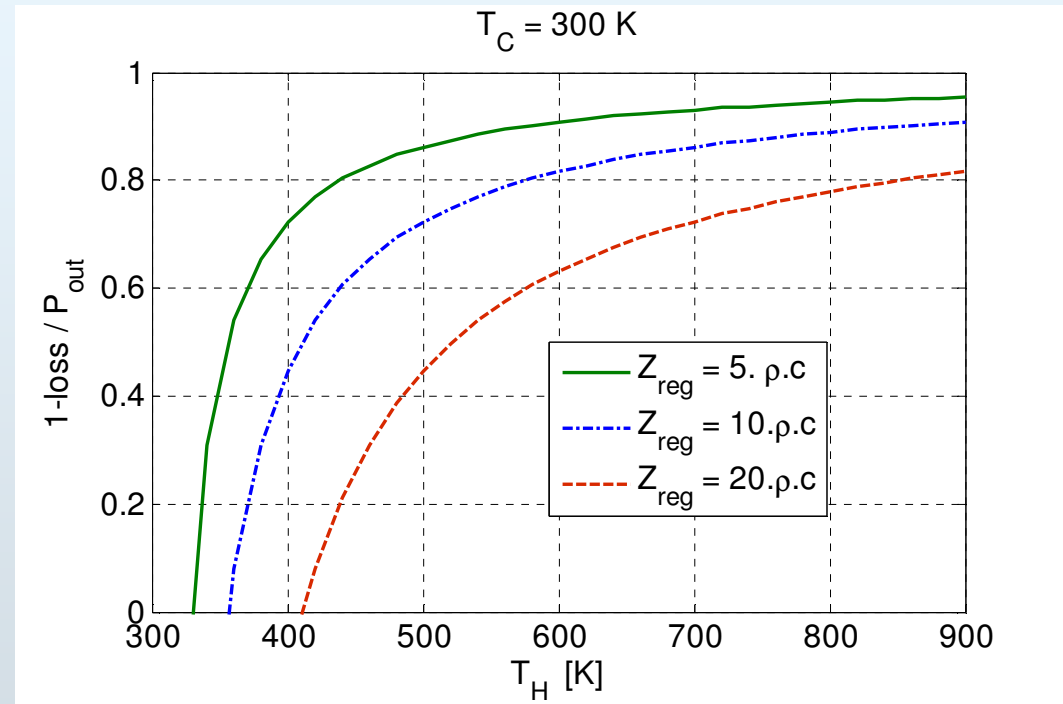
$$P_{Load} = \frac{A_0 \cdot p_1^2}{2 \cdot \text{Re}(Z_L)}$$

## General system aspects

- Impact of average regenerator impedance on available acoustic power

### Assumptions:

- “ideal” 1 stage engine
  - $\omega\tau \Rightarrow 0$
  - $R \Rightarrow 0$
  - $\eta_2 \Rightarrow 1$
- Impedance setting  $\neq f$  ( $R_{reg}$ )
- loss calculated for  $\frac{1}{2}\lambda$  resonator
- small signal regime (laminar)

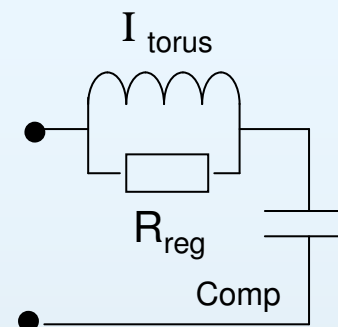


- Onset and small signal behavior depends on configuration and geometry only
- Acoustic loop power times gain less than acoustic loss for  $Z_{reg} = 20. \rho.c$  and  $T_H < 410 \text{ K}$

**Average regenerator impedance should be set to a minimum value for low and medium operating temperatures**

## Reduction of average regenerator impedance

- For default torus or bypass geometry
  - $Z_{reg}$  commonly set to  $> 15 \cdot \rho \cdot c$
  - $Inertance_{torus} \ll R_{regenerator}$
- Timing or phase  $(p_a, v_a) = f(R_{reg})$ 
  - $R_{reg} \Rightarrow 0, Phase \Rightarrow 90^\circ$

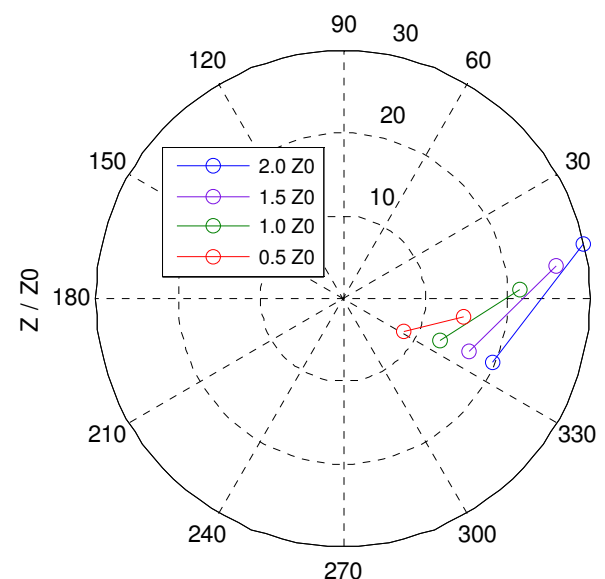


Typical impedance versus  $R_{reg} / \rho \cdot c$

### Consequences:

- More regenerator mass (length) than required from heat capacity ratio
- Low system power density
- Efficiency proportional with regenerator flow resistance but less power

**Little options left for impedance reduction**

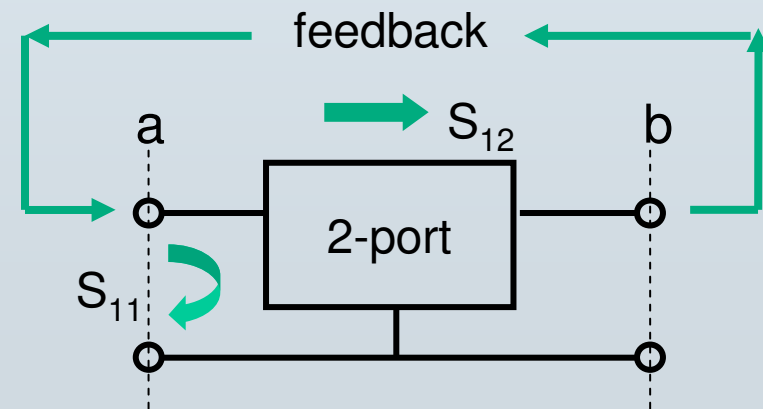
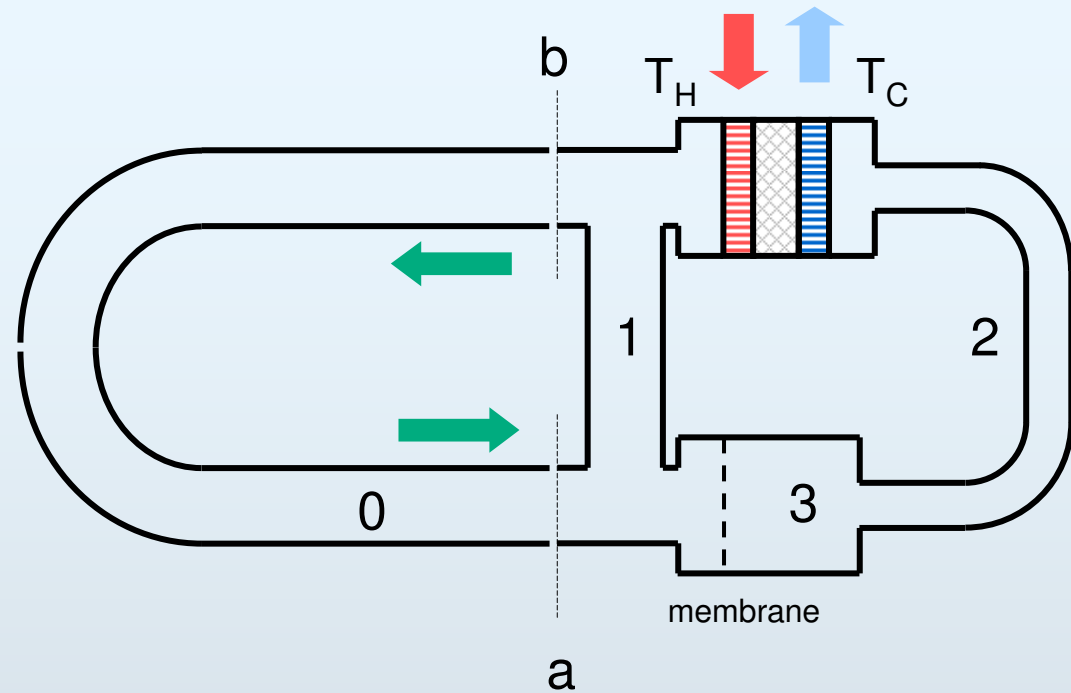


# Hybrid configuration

Back to basics !

(re-arranging acoustic circuitry and apply all "tricks" from the past)

- Traveling wave loop (0)
  - Initial used by Ceperly for timing
  - Now used to avoid high local amplitudes
- Torus or bypass
  - Compliance (3)
  - Inertance (2)
- Velocity reduction
  - Additional bypass (1)
  - $A_{reg} > A_0$



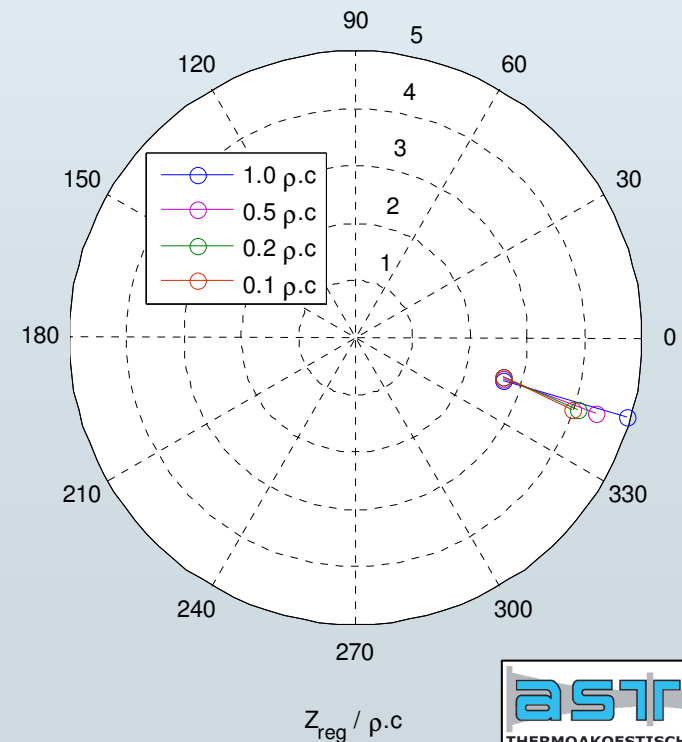
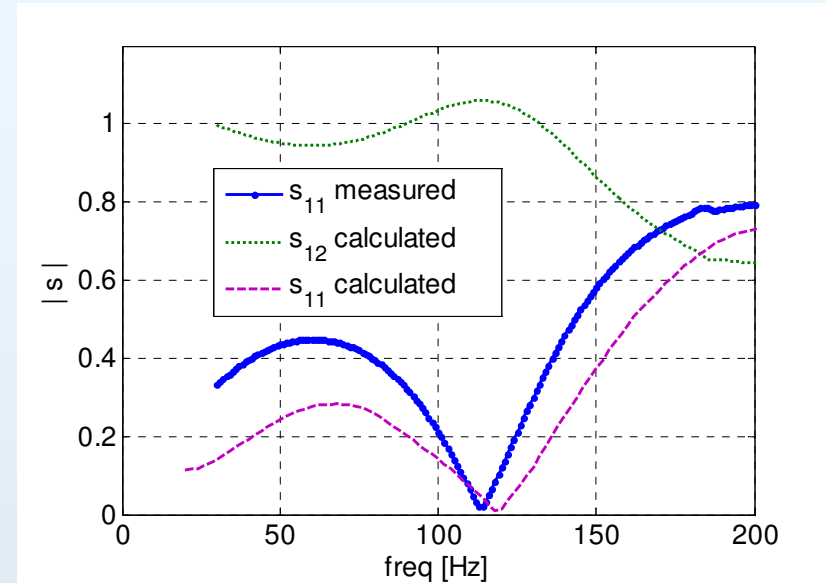
# Hybrid configuration

## Feedback loop

- Travelling wave if
  - $S_{11} \Rightarrow 0$  (no reflection)

$$Z_0 = \frac{\rho \cdot c}{A_0}$$

- Oscillation if
  - net forward acoustic power gain  $\geq 1$
  - phase delay of 2-port plus feed back loop equals  $2 \cdot \pi$  ( $= \lambda$ )
- Average regenerator impedance
  - absolute value relatively low
  - phase nearly independent of regenerator flow resistance



# Hybrid configuration

Comparison with the “classic” torus or bypass configuration

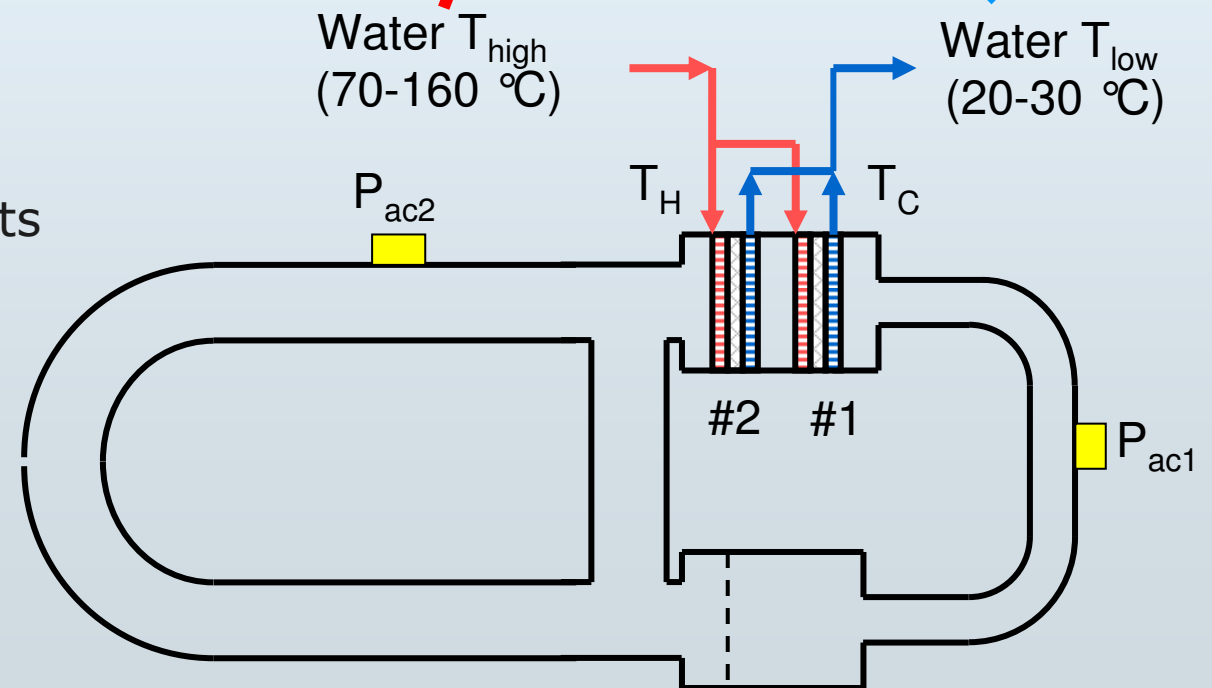
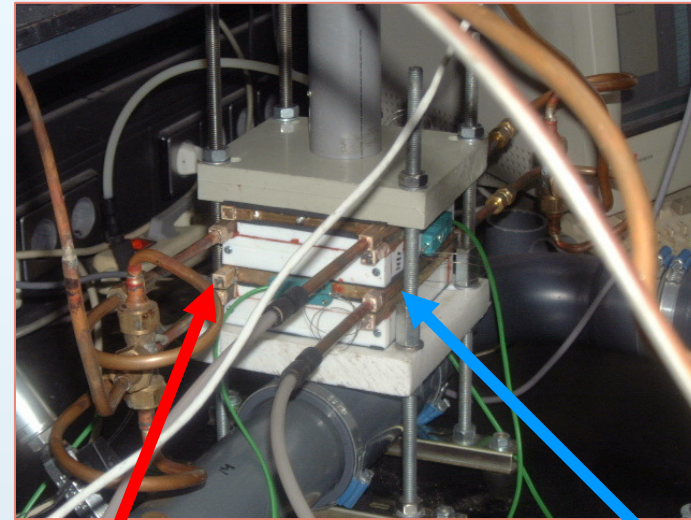
- Regenerator impedance can be set to arbitrary (lower) value
  - Absolute value depends on geometry and regenerator flow resistance
  - Phase (timing) depends primarily on geometry
- Regenerator mass can be minimized
  - Lower onset temperature
  - Steeper slope  $\Delta P_{ac} / \Delta T$
  - Becomes a function of acoustic power (related to heat capacity)
  - Efficiency improves for lower regenerator flow resistance (as should be the case for thermo-dynamic systems in general)
- Reduced impedance allows for multiple regenerator units
  - Extended “soft spot”
- High acoustic power at given amplitude (near traveling waves)
  - System more compact
  - Low acoustic loss / power ratio (no extreme local amplitudes)
- Streaming suppression (e.g. membrane) on convenient location



# Experimental verification

## Measurement setup 2 stage engine

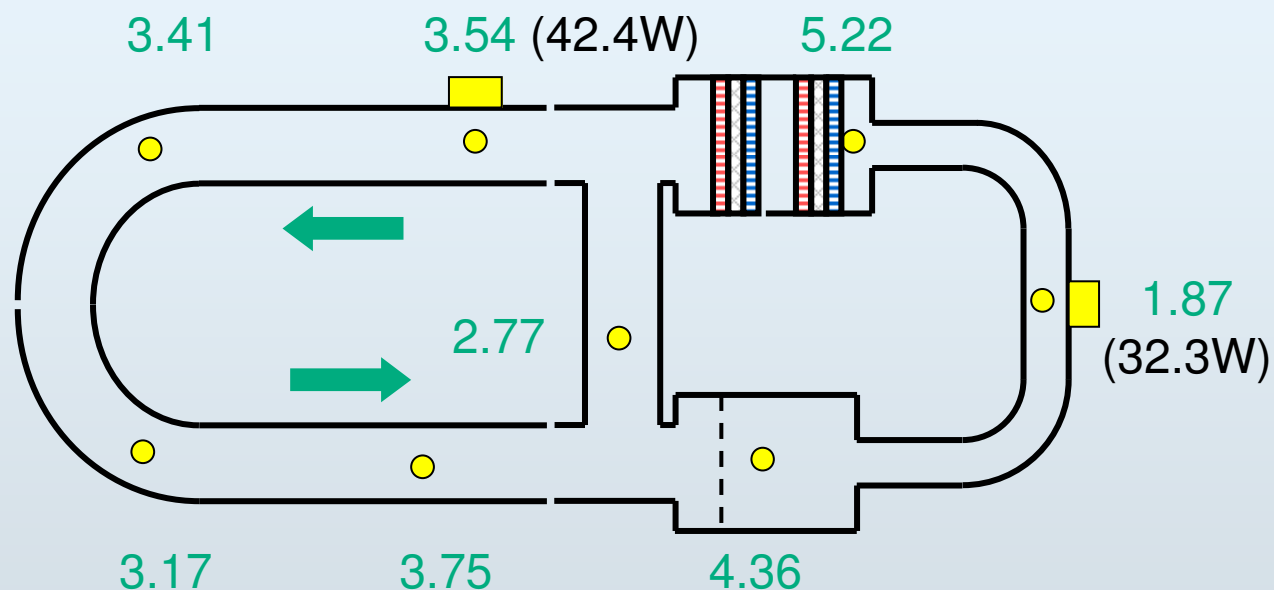
- Water circuits
  - High temperature
    - Gas fired water heater
    - Max 160 °C (10 bar)
  - Low temperature
    - Car radiator to air
    - Flow 1.5 l.min<sup>-1</sup>
    - 20-30 °C
- Acoustic power measurements
  - Pressure gradient method
- Temperature measurements
  - Water in – out ( $T_0, T_3$ )
  - Regenerator high – low ( $T_2, T_1$ )



## Experimental verification

Typical pressure amplitude distribution at oscillation (**Measured Values in kPa**)

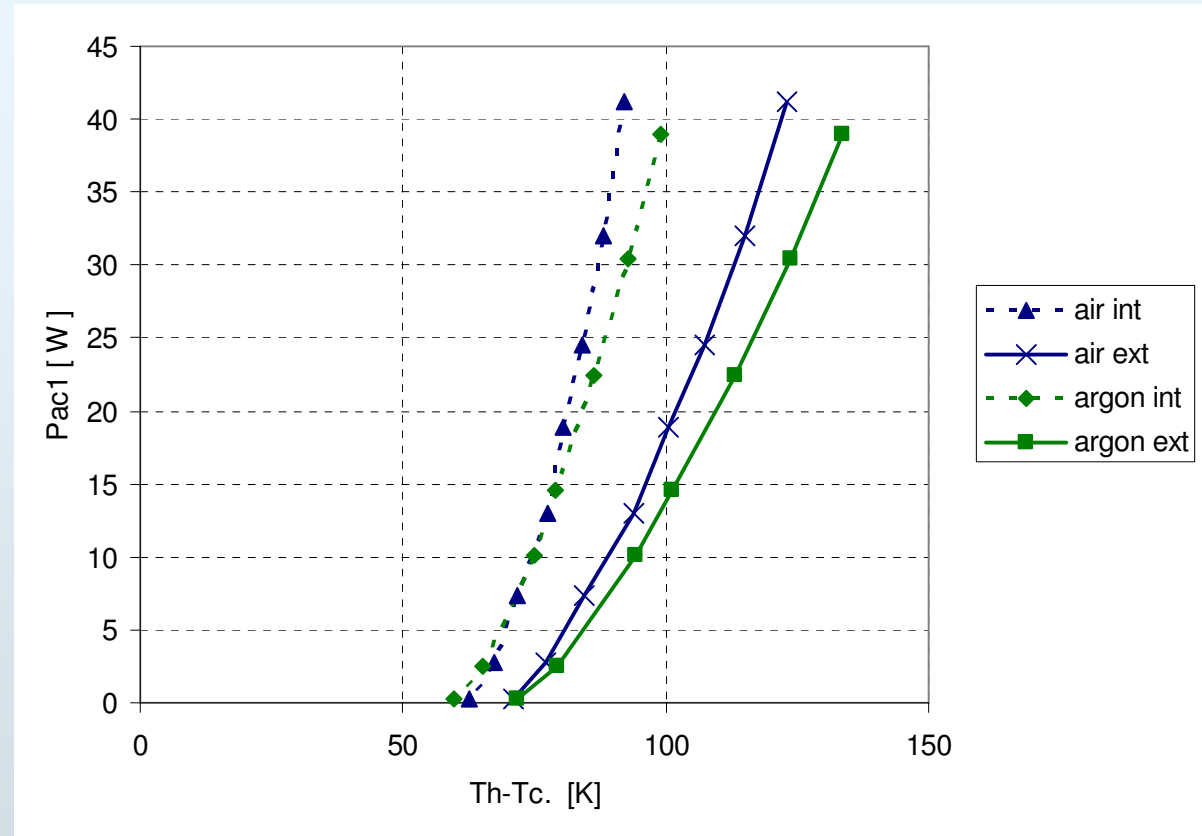
- $D_0 = 67 \text{ mm}$
- $A_{\text{reg}} = 100 \times 120 \text{ mm}$
- $L_{\text{reg}} = 1.58 \text{ mm}$
- $\text{Por} = 0.74$
- $L_{\text{hex}} = 0.56 \text{ mm}$
  
- Air @ 98 kPa
- Frequency = 132 Hz
- $T_{\text{water\_in}} = 148 \text{ }^\circ\text{C}$
- $T_{\text{water\_uit}} = 28 \text{ }^\circ\text{C}$



- Near traveling wave in feedback loop ( $\text{SWR} < 1.2$ )
- No extreme amplitude maxima or minima
- High acoustic power while only 3.5% drive ratio in feed back loop (“resonator”)
- Reduced regenerator impedance ( $Z_{\text{reg}} \approx 3 \rho \cdot c$ )

# Experimental verification

- Onset temperature same for air and argon
- $\Delta T_{\text{ext}} - \Delta T_{\text{int}}$  proportional with power
  - $G_{\text{HEX}} \approx 7 \text{ W.K}^{-1}$  (air)
- Hex temperature drop related to gas heat conductivity
- Slope  $\Delta \text{Pac} / \Delta T$  related to viscosity
- Slope  $\Delta \text{Pac} / \Delta T$  increases with power
  - better heat exchange (Re, Nu)
  - Higher efficiency



$\Delta T_{\text{Onset}}$



$\Delta T_{\text{Available}}$

## Conclusions

- Classic standing wave resonator combined with a high regenerator impedance (set by torus or bypass) impede low and medium temperature applications
- To overcome these limitations an example of a novel hybrid configuration is proposed
- Experimental results agree well with theory behind and indicate a significant improvement in onset temperature and power density
  - With air at atmospheric pressure
    - applied onset temperature difference 63 K
    - acoustic power 42 W at 3.5% drive ratio
- For efficient low temperature operation at 160 °C onset temperature and hex temperature drop still to high
- Hybrid configurations allows for further optimizing TA engines in the low and medium operation temperature regime